Introduction

This driver for Atmel® | SMART ARM®-based microcontrollers provides an interface for the configuration and management of the on-chip General-Purpose Input/Output (GPIO) controller with both interrupt and event support.

Devices from the following series can use this module:
• Atmel | SMART SAM4L

The outline of this documentation is as follows:
• Prerequisites
• Module Overview
• Special Considerations
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• Examples
• API Overview
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1. **Software License**

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2. **Prerequisites**

The GPIO module depends on the following modules:

- System Clock Management (Sysclock) for clock control
- Global interrupt management for enabling or disabling interrupts
- Common IOPORT API for basic GPIO functions
3. **Module Overview**

The General Purpose Input/Output Controller (GPIO) controls the I/O pins of the microcontroller. Each GPIO pin may be used as a general-purpose I/O or be assigned to a function of an embedded peripheral. The GPIO is configured using the Peripheral Bus (PB).
4. Special Considerations

There are no special considerations for this module.
5. Extra Information

For extra information, see Extra Information for GPIO. This includes:

- Acronyms
- Dependencies
- Errata
- Module History
6. **Examples**

For a list of examples related to this driver, see *Examples for GPIO.*
7. API Overview

7.1. Variable and Type Definitions

7.1.1. Type gpio_pin_callback_t

```c
typedef void(* gpio_pin_callback_t )(void)
```

The interrupt handler can be configured to do a function callback, the callback function must match the gpio_pin_callback_t type.

7.2. Function Definitions

7.2.1. Interrupt Support

The GPIO can be configured to generate an interrupt when it detects a change on a GPIO pin.

7.2.1.1. Function gpio_set_pin_callback()

Set callback for given GPIO pin.

```c
bool gpio_set_pin_callback( 
    ioport_pin_t pin, 
    gpio_pin_callback_t callback, 
    uint8_t irq_level)
```

<table>
<thead>
<tr>
<th>Data direction</th>
<th>Parameter name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[in]</td>
<td>pin</td>
<td>The pin number</td>
</tr>
<tr>
<td>[in]</td>
<td>callback</td>
<td>callback function pointer</td>
</tr>
<tr>
<td>[in]</td>
<td>irq_level</td>
<td>interrupt level</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Return value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>true</td>
<td>Set successfully</td>
</tr>
<tr>
<td>false</td>
<td>Wrong parameters or maximum number of interrupt sources has been exceeding</td>
</tr>
</tbody>
</table>

7.2.1.2. Function gpio_enable_pin_interrupt()

Enable the interrupt of a pin.

```c
void gpio_enable_pin_interrupt( 
    ioport_pin_t pin)
```
### 7.2.1.3. Function gpio_disable_pin_interrupt()

Disable the interrupt of a pin.

```c
void gpio_disable_pin_interrupt(
    ioport_pin_t pin)
```

### 7.2.1.4. Function gpio_get_pin_interrupt_flag()

Get the interrupt flag of a pin.

```c
uint32_t gpio_get_pin_interrupt_flag(
    ioport_pin_t pin)
```

### 7.2.1.5. Function gpio_clear_pin_interrupt_flag()

Clear the interrupt flag of a pin.

```c
void gpio_clear_pin_interrupt_flag(
    ioport_pin_t pin)
```

### 7.2.2. Peripheral Event System Support

The GPIO can be programmed to output peripheral events whenever an interrupt condition is detected, such as pin value change, or only when a rising or falling edge is detected.
7.2.2.1. Function gpio_enable_pin_periph_event()

Enable the peripheral event generation of a pin.

```c
void gpio_enable_pin_periph_event(
    ioport_pin_t pin)
```

Table 7-8 Parameters

<table>
<thead>
<tr>
<th>Data direction</th>
<th>Parameter name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[in]</td>
<td>pin</td>
<td>The pin number</td>
</tr>
</tbody>
</table>

7.2.2.2. Function gpio_disable_pin_periph_event()

Disable the peripheral event generation of a pin.

```c
void gpio_disable_pin_periph_event(
    ioport_pin_t pin)
```

Table 7-9 Parameters

<table>
<thead>
<tr>
<th>Data direction</th>
<th>Parameter name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[in]</td>
<td>pin</td>
<td>The pin number</td>
</tr>
</tbody>
</table>
8. Extra Information for GPIO

8.1. Acronyms

Below is a table listing the acronyms used in this module, along with their intended meanings.

<table>
<thead>
<tr>
<th>Acronym</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>PB</td>
<td>Peripheral Bus</td>
</tr>
<tr>
<td>QSG</td>
<td>Quick Start Guide</td>
</tr>
</tbody>
</table>

8.2. Dependencies

This driver has the following dependencies:

- Power Management

If the CPU enters a sleep mode that disables clocks used by the GPIO, the GPIO will stop functioning and resume operation after the system wakes up from sleep mode. If a peripheral function is configured for a GPIO pin, the peripheral will be able to control the GPIO pin even if the GPIO clock is stopped.

- Clocks

The GPIO is connected to a Peripheral Bus clock (CLK_GPIO). This clock is generated by the Power Manager. CLK_GPIO is enabled at reset, and can be disabled by writing to the Power Manager. CLK_GPIO must be enabled in order to access the configuration registers of the GPIO or to use the GPIO interrupts. After configuring the GPIO, the CLK_GPIO can be disabled by writing to the Power Manager if interrupts are not used.

- Interrupts

The GPIO interrupt request lines are connected to the NVIC. Using the GPIO interrupts requires the NVIC to be programmed first.

- Peripheral Events

The GPIO peripheral events are connected via the Peripheral Event System.

- Debug Operation

When an external debugger forces the CPU into debug mode, the GPIO continues normal operation. If the GPIO is configured in a way that requires it to be periodically serviced by the CPU through interrupts or similar, improper operation or data loss may result during debugging.

8.3. Errata

There are no errata related to this driver.

8.4. Module History

An overview of the module history is presented in the table below, with details on the enhancements and fixes made to the module since its first release. The current version of this corresponds to the newest version in the table.
### Changelog

Initial document release
9. **Examples for GPIO**

This is a list of the available Quick Start guides (QSGs) and example applications for **SAM4L General-Purpose Input/Output (GPIO) Driver**. QSGs are simple examples with step-by-step instructions to configure and use this driver in a selection of use cases. Note that a QSG can be compiled as a standalone application or be added to the user application.

- Example
10. Quick Start Guide for the GPIO driver

This is the quick start guide for the group.sam_drivers_gpio, with step-by-step instructions on how to configure and use the driver for a specific use case.

The use cases contain several code fragments. The code fragments in the steps for setup can be copied into a custom initialization function, while the steps for usage can be copied into, e.g., the main application function.

10.1. Use Cases

- GPIO Interrupt Usage

10.2. GPIO Interrupt Usage

This use case will demonstrate how to configure a pin(PC03) to trigger an interrupt on SAM4L-EK board.

10.3. Setup Steps

10.3.1. Prerequisites

This module requires the following service:

- Clock management
- Common IOPORT (for GPIO)
11. Example

Add this to the main loop or a setup function:

```c
/* Configure push button 0 to trigger an interrupt on falling edge */
ioport_set_pin_dir(EXAMPLE_BUTTON_INT, IOPORT_DIR_INPUT);
ioport_set_pin_mode(EXAMPLE_BUTTON_INT, IOPORT_MODE_PULLUP | IOPORT_MODE_GLITCH_FILTER);
ioport_set_pin_sense_mode(EXAMPLE_BUTTON_INT, IOPORT_SENSE_FALLING);
if (!gpio_set_pin_callback(EXAMPLE_BUTTON_INT, pb0_callback, 1)) {
    printf("Set pin callback failure!\r\n");
    while (1) {
    }
}
gpio_enable_pin_interrupt(EXAMPLE_BUTTON_INT);
```

1. Initialize a pin to trigger an interrupt. Here, we initialize PC03 as an input pin with pull up and glitch filter and to generate an interrupt on a falling edge.

```c
ioport_set_pin_dir(EXAMPLE_BUTTON_INT, IOPORT_DIR_INPUT);
ioport_set_pin_mode(EXAMPLE_BUTTON_INT, IOPORT_MODE_PULLUP | IOPORT_MODE_GLITCH_FILTER);
ioport_set_pin_sense_mode(EXAMPLE_BUTTON_INT, IOPORT_SENSE_FALLING);
```

2. Set a callback for the pin interrupt.

```c
if (!gpio_set_pin_callback(EXAMPLE_BUTTON_INT, pb0_callback, 1)) {
    printf("Set pin callback failure!\r\n");
    while (1) {
    }
}
```

3. Enable pin interrupt.

```c
gpio_enable_pin_interrupt(EXAMPLE_BUTTON_INT);
```

11.1. Interrupt Usage

When an interrupt happens on a pin, it will execute your callback function.

```c
static void pb0_callback(void)
{
    /* Handle pin interrupt here e.g. toggle an LED */
    LED_Toggle(LED0);
}
```
12. Document Revision History

<table>
<thead>
<tr>
<th>Doc. Rev.</th>
<th>Date</th>
<th>Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>42280B</td>
<td>07/2015</td>
<td>Updated title of application note and added list of supported devices</td>
</tr>
<tr>
<td>42280A</td>
<td>05/2014</td>
<td>Initial document release</td>
</tr>
</tbody>
</table>